..... 1

1.1 1

1.2 2

..... 3

2.1 3

2.2 4

2.3 4

2.4 8

..... 12

3.1 12

3.2 12

3.3 13

3.4 19

..... 35

4.1 35

4.2 35

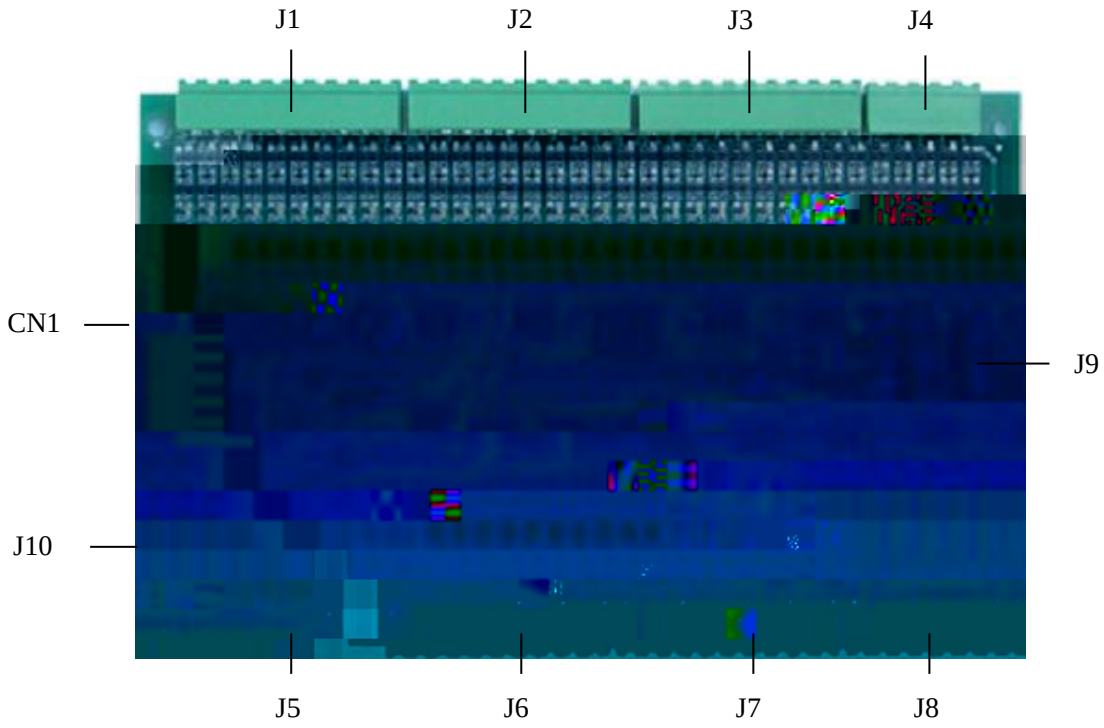
4.3 35

..... 37

1.1

1.2

2.1

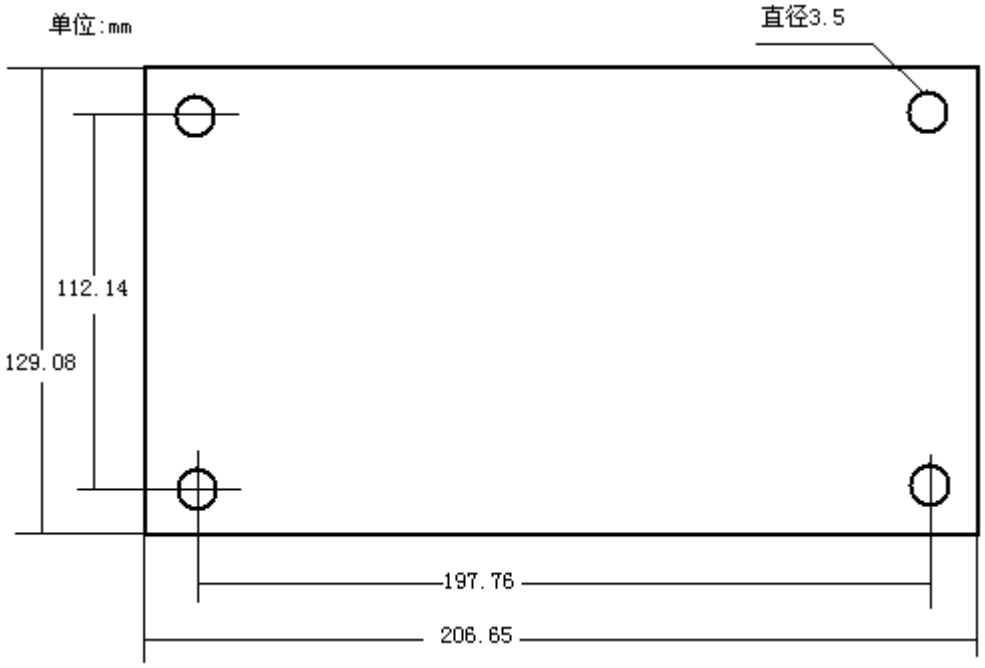


1 BL2000-FTB-V1



2

2.2

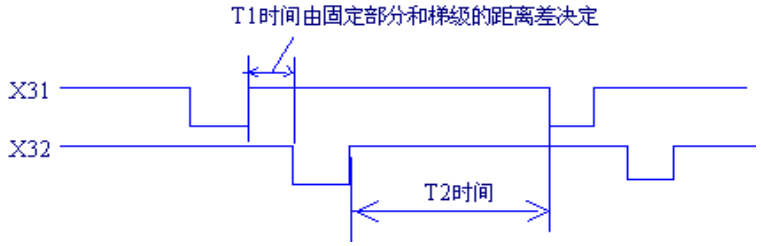


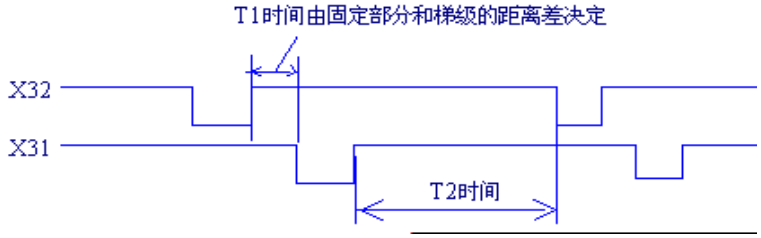
2.3

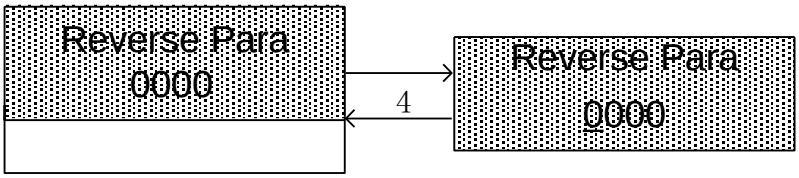
2.3.1 24V

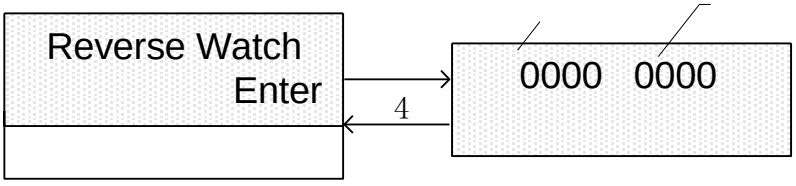


2.4


T1时间由固定部分和梯级的距离差决定
X31
X32
T2时间


T1时间由固定部分和梯级的距离差决定
X32
X31
T2时间

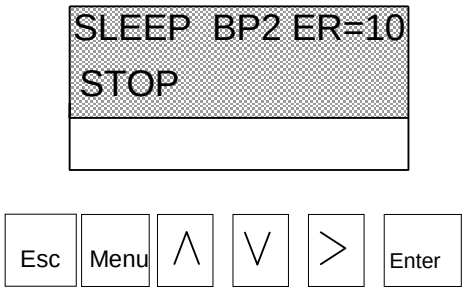

Reverse Para
0000
4
Reverse Para
0000


Reverse Watch
Enter
4
0000 0000

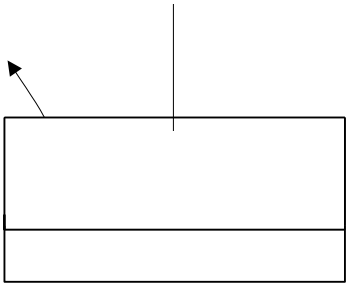
L0 L1 L2 L3 L4 L5 L6 L7 L8 L9 COM7

3.1

3.2



3.3



a

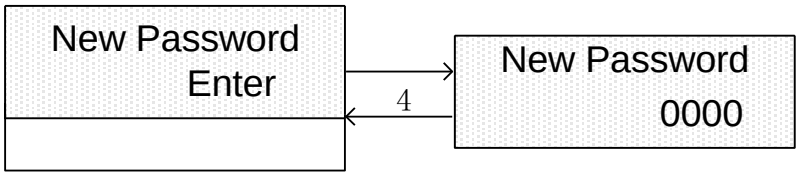
1		I/O Input	
2		Reverse Watch	
3		Run Report	
4		Fault Report	
5		Software No	

1		Set Time			
2		Start Time	00 00*		
3		Stop Time	00 00*		
4		Oil Type	0		0 1
5		Lubricant Time	48*	0 999	

6

13		KJT Check Enable	NO*		
14		Vice Brake Enable	Yes*		
15	1	Vice Brake F1	NO*		
16	1	Vice Brake F2	NO*		
17	Y11	Y11 Output Type	ON*		
18	1	Reverse 1 Enable	NO*		

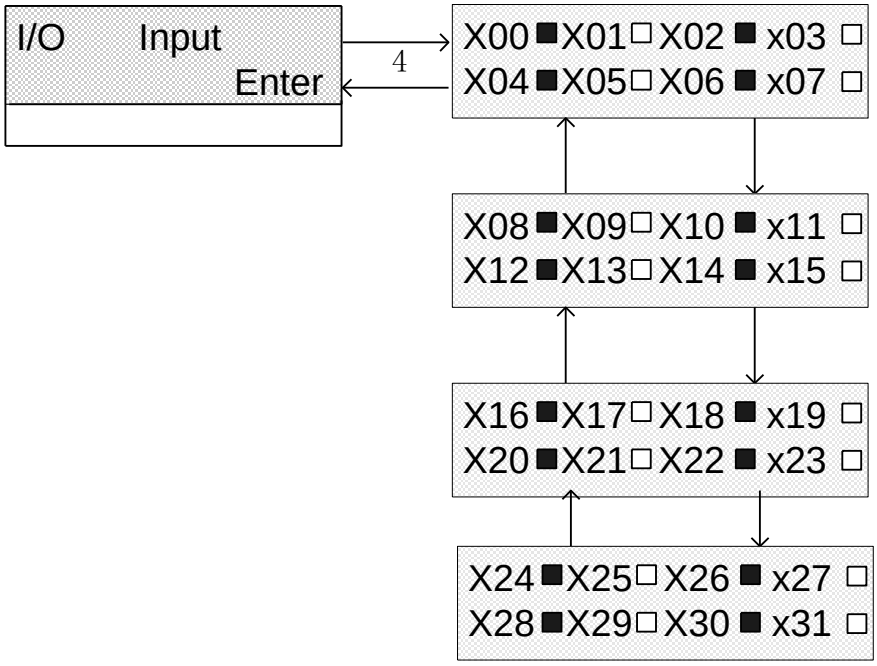
1		Factory para	NO		
2		Read Para			
3		Write Para			
4	Y10	Y10 Function	0*	0-11	
5	Y11				


New Password
Enter
4
New Password
0000

3.4

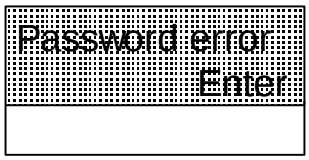
3.4.1

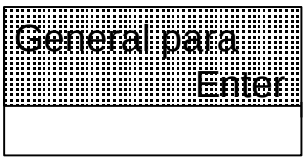
1

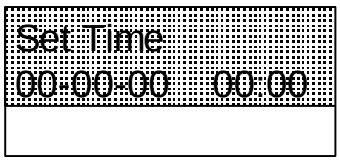

I/O Input
Enter
4
X00 X01 X02 x03
X04 X05 X06 x07
X08 X09 X10 x11
X12 X13 X14 x15
X16 X17 X18 x19
X20 X21 X22 x23
X24 X25 X26 x27
X28 X29 X30 x31

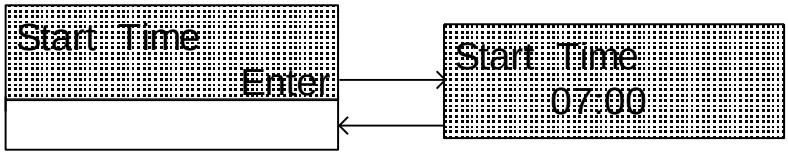
1 0

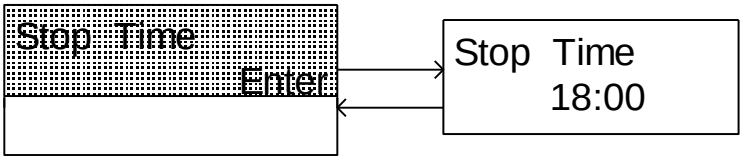

Reverse Watch
Enter

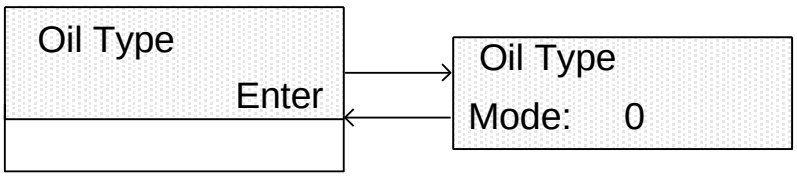

Password error
Enter


General para
Enter

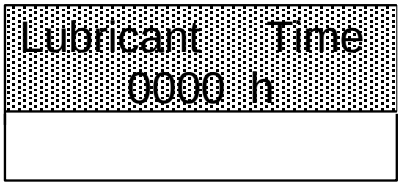

Set Time
00:00:00 00:00

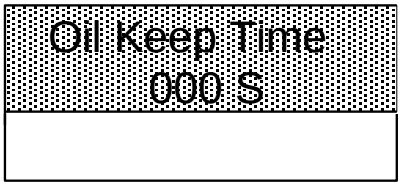

Start Time
Enter
Start Time
07:00


Stop Time
Enter
Stop Time
18:00

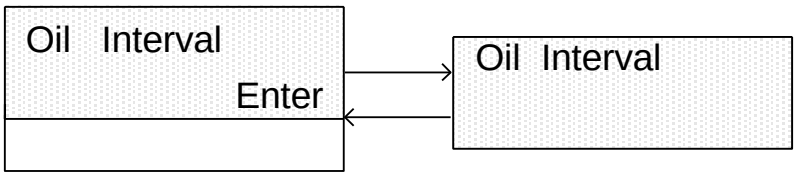

Oil Type
Enter
Oil Type
Mode: 0

0 1

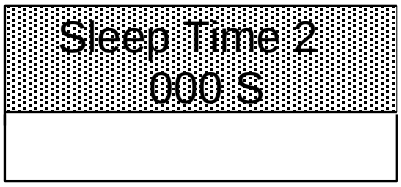

Lubricant Time
0000 h


Oil Keep Time
000 S

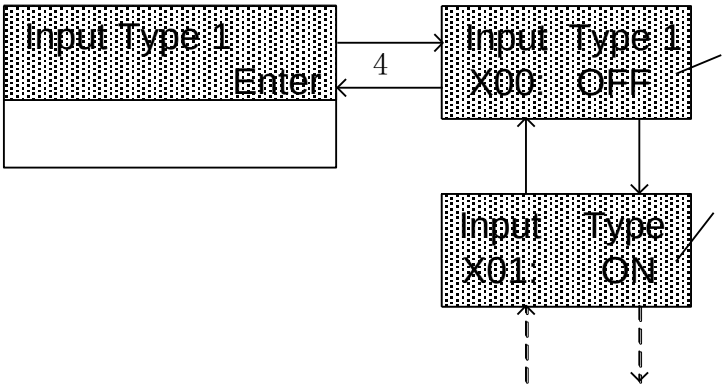
7

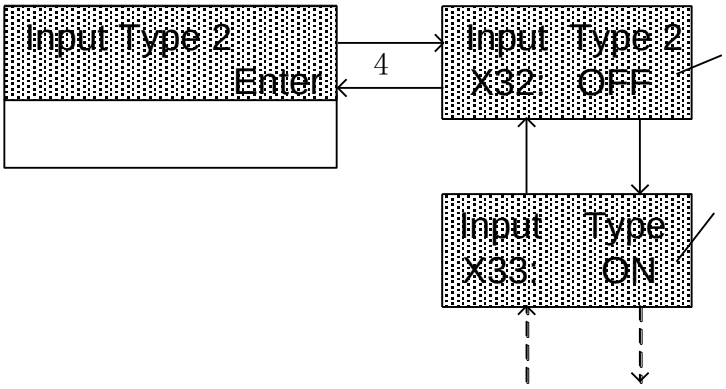

Oil Interval
Enter
Oil Interval

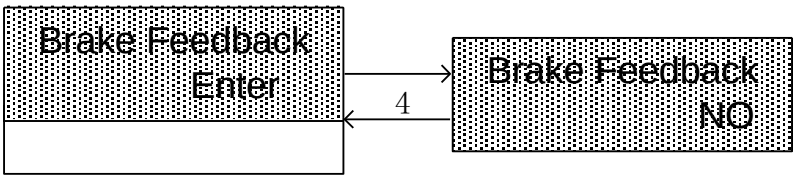
1

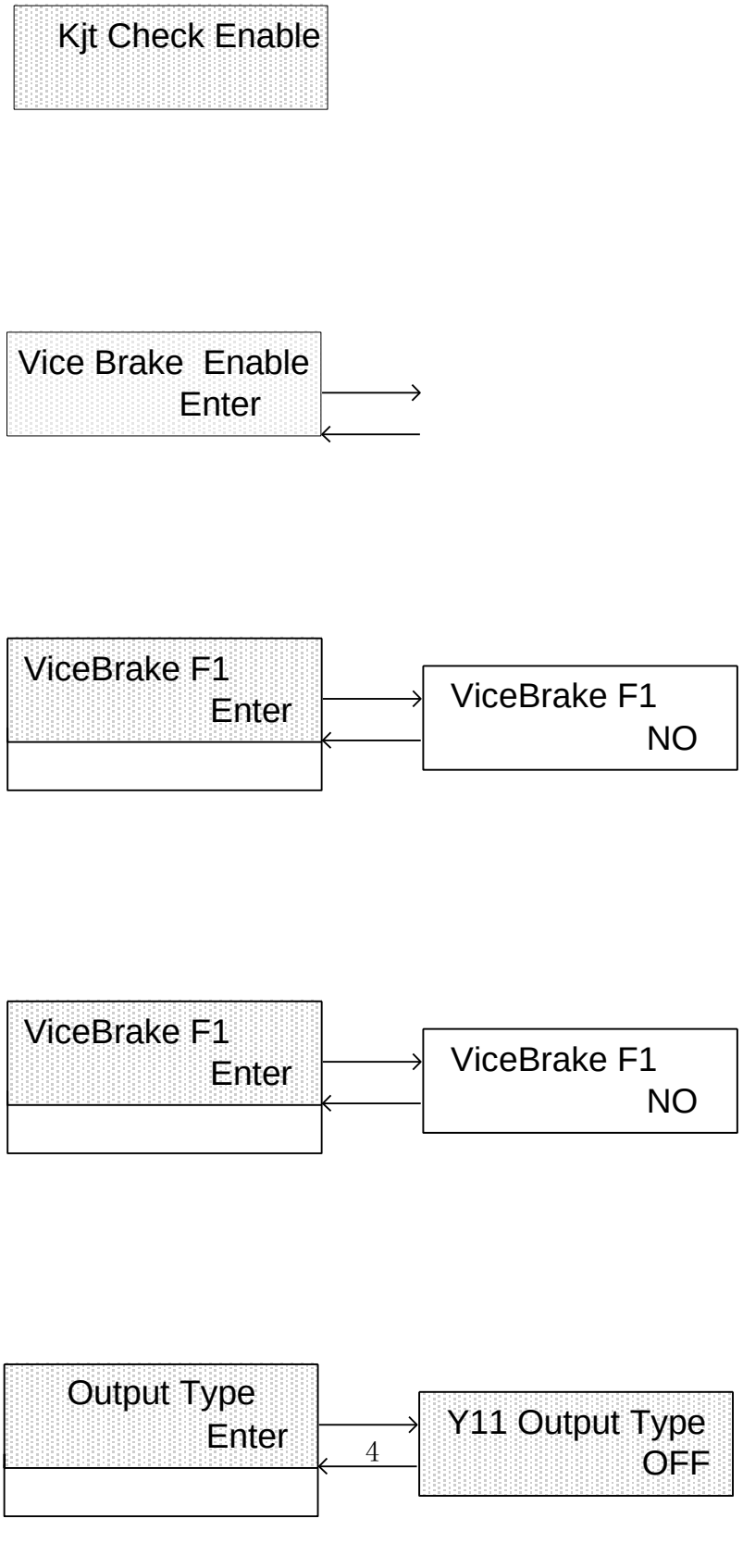

Sleep Time 2
000 S

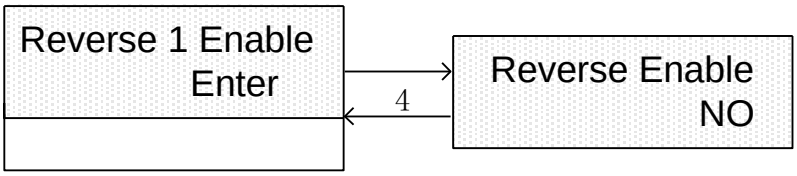
5

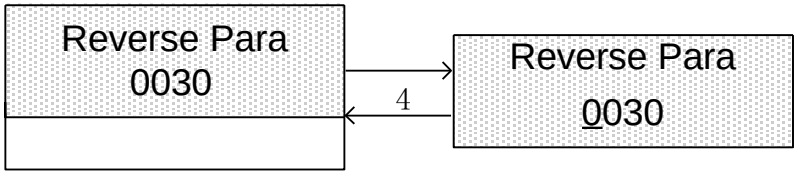

Input Type 1
Enter
4
Input Type 1
X00 OFF
Input Type
X01 ON

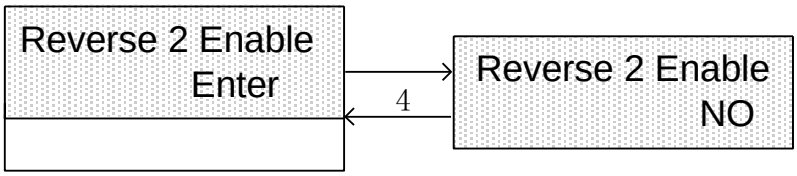

Input Type 2
Enter
4
Input Type 2
X32 OFF
Input Type
X33 ON

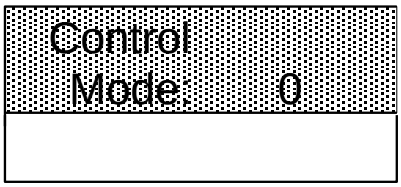

Brake Feedback
Enter
4
Brake Feedback
NO

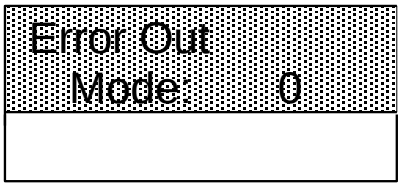

Kjt Check Enable
Vice Brake Enable
Enter
ViceBrake F1
Enter
ViceBrake F1
NO
ViceBrake F1
Enter
ViceBrake F1
NO
Output Type
Enter
4
Y11 Output Type
OFF

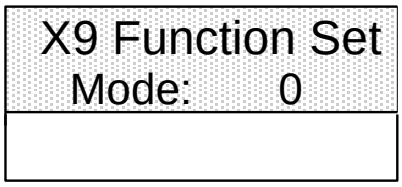

Reverse 1 Enable
Enter
4
Reverse Enable
NO

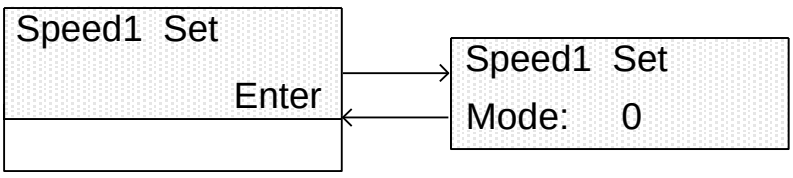

Reverse Para
0030
4
Reverse Para
0030


Reverse 2 Enable
Enter
4
Reverse 2 Enable
NO


Control
Mode: 0


Error Out
Mode: 0

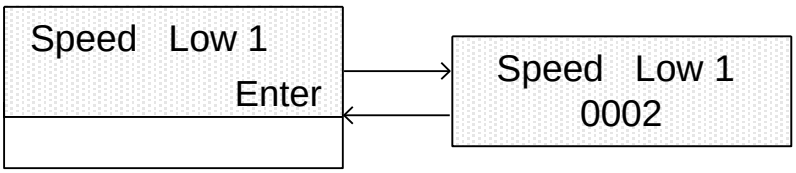

X9 Function Set
Mode: 0

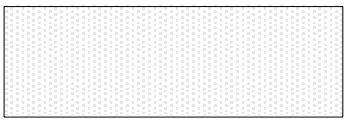

Speed1 Set
Enter
Speed1 Set
Mode: 0

1

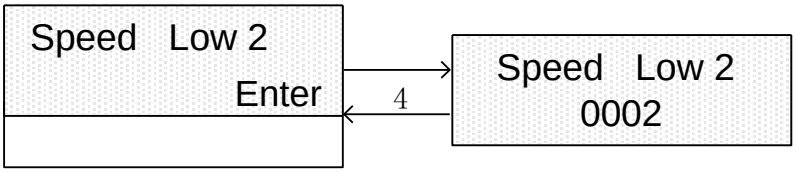
2 2

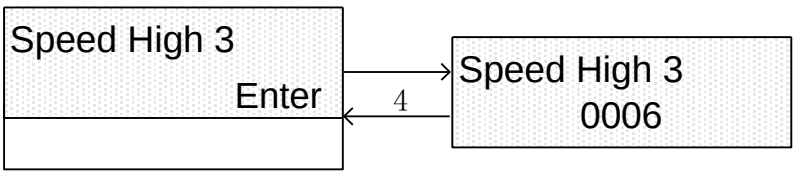
2

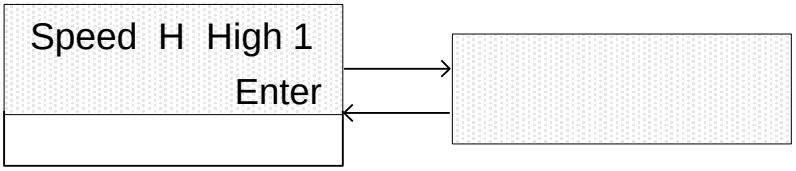


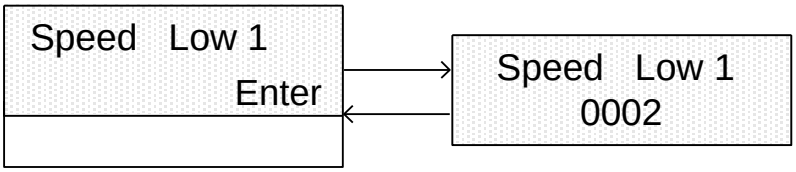


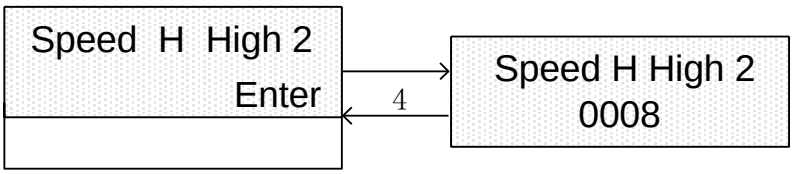
Speed High 2 Enrn

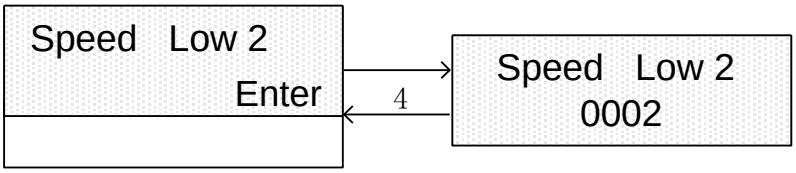


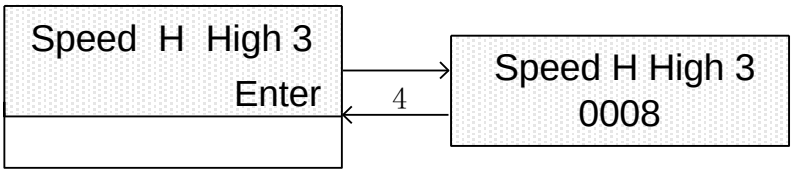

Speed High 3
Enter
4
Speed High 3
0006

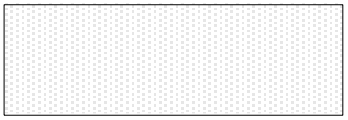

Speed H High 1
Enter

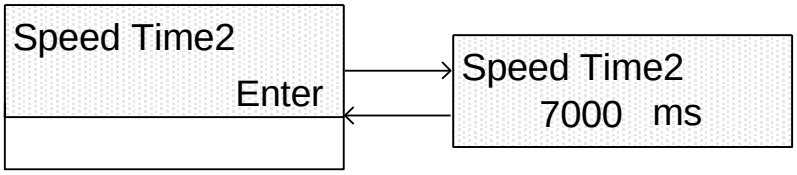

Speed Low 1
Enter
Speed Low 1
0002

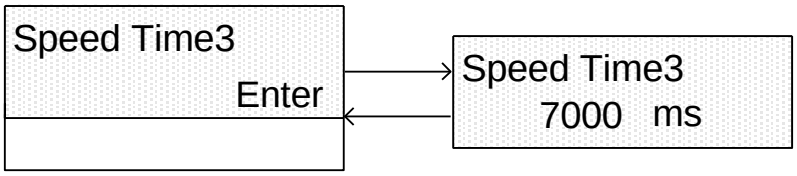

Speed H High 2
Enter
4
Speed H High 2
0008

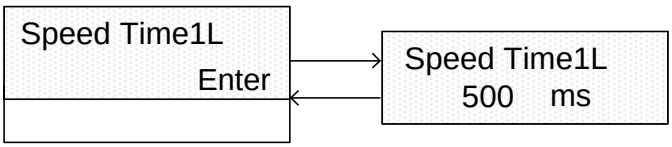

Speed Low 2
Enter
4
Speed Low 2
0002

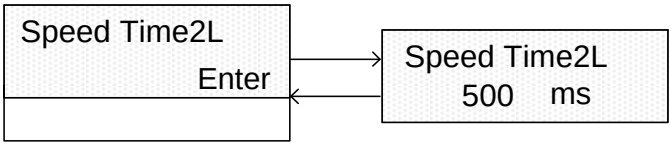

Speed H High 3
Enter
4
Speed H High 3
0008

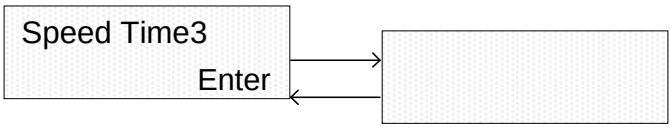



Speed Time2
Enter
Speed Time2
7000 ms

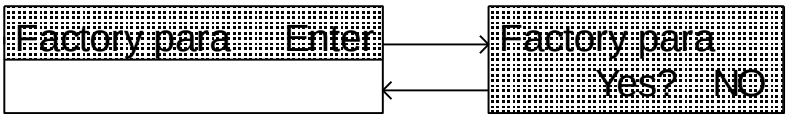

Speed Time3
Enter
Speed Time3
7000 ms

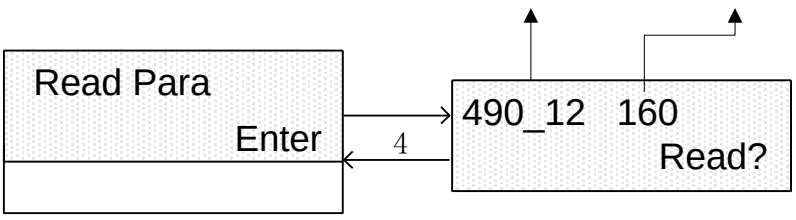

Speed Time1L
Enter
Speed Time1L
500 ms

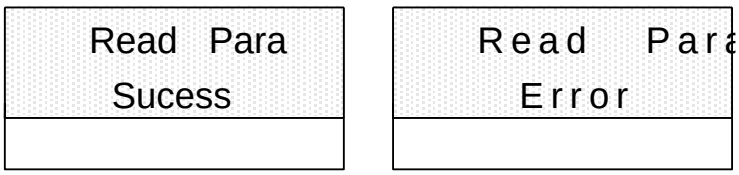

Speed Time2L
Enter
Speed Time2L
500 ms


Speed Time3
Enter

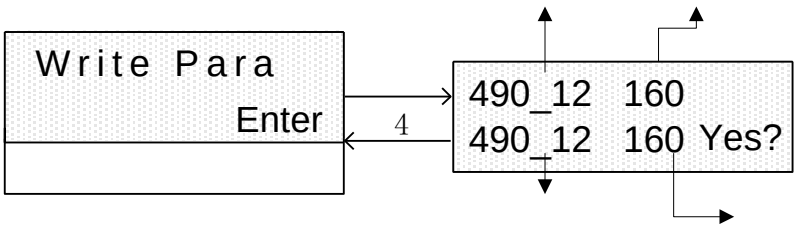

Special para Enter


Factory para Enter
Factory para
Yes? NO

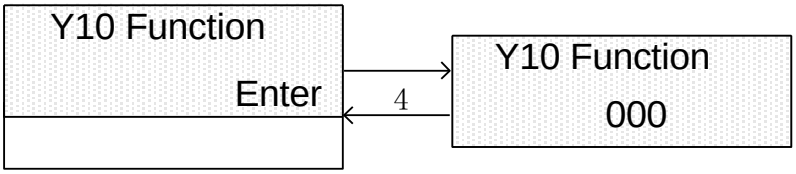

Read Para
Enter
4
490_12 160
Read?



3



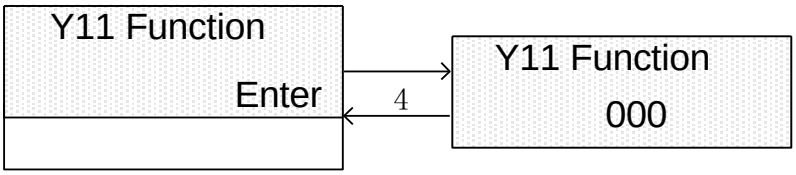
4 Y10



0-11 0

	1	2	3	4	5	6	7	8	9	10	11
	Y0	Y1	Y2	Y3	Y4	Y5	Y6	Y7	Y8	Y9	Y11

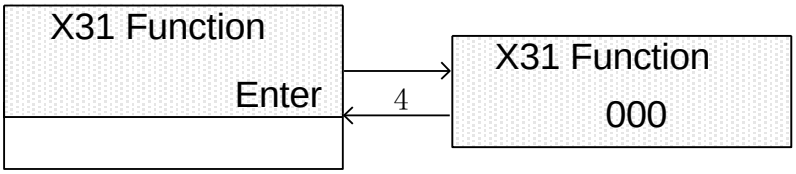
5 Y11



0-11 0

	1	2	3	4	5	6	7	8	9	10	11
	Y0	Y1	Y2	Y3	Y4	Y5	Y6	Y7	Y8	Y9	Y10

6 X31



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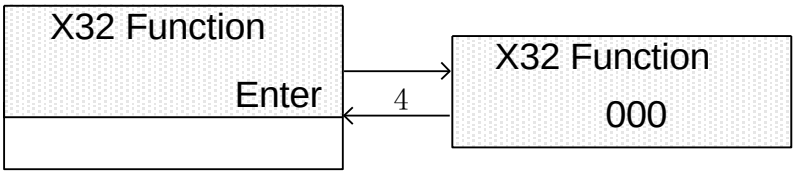
	X0	X1	X2	X3	X4	X5	X6	X7	X8	X9	X10
	12	13	14	15	16	17	18	19	20	21	22
	X11	X12	X13	X14	X15	X16	X17	X18	X19	X20	X21
	23	24	25	26	27	28	29	30	31		
	X22	X23	X24	X25	X26	X27	X28	X29	X30		

7 X32



0-31 0 2

	1	2	3	4	5	6	7	8	9	10	11
	X0	X1	X2	X3	X4	X5	X6	X7	X8	X9	X10

4.1

